

Field Theory of Neural Networks

A Tutorial (Part 3)

- <https://www2.phys.uniroma1.it/doc/crisanti/Teach/DFT/Files/CNS-19.pdf>



Outline

- Model
 - Dynamic Field Theory
 - Disorder Average
 - Dynamic Mean Field Theory
 - Stability and Replicas
 - Chaotic Solution and Lyapunov Exponent
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- H. Sompolinsky, A. C., H.-J. Sommers
Phys. Rev. Lett. 61, 259 (1988)
 - A. C, H. Sompolinsky,
Phys. Rev. E. 98, 062120 (2018)



The Model

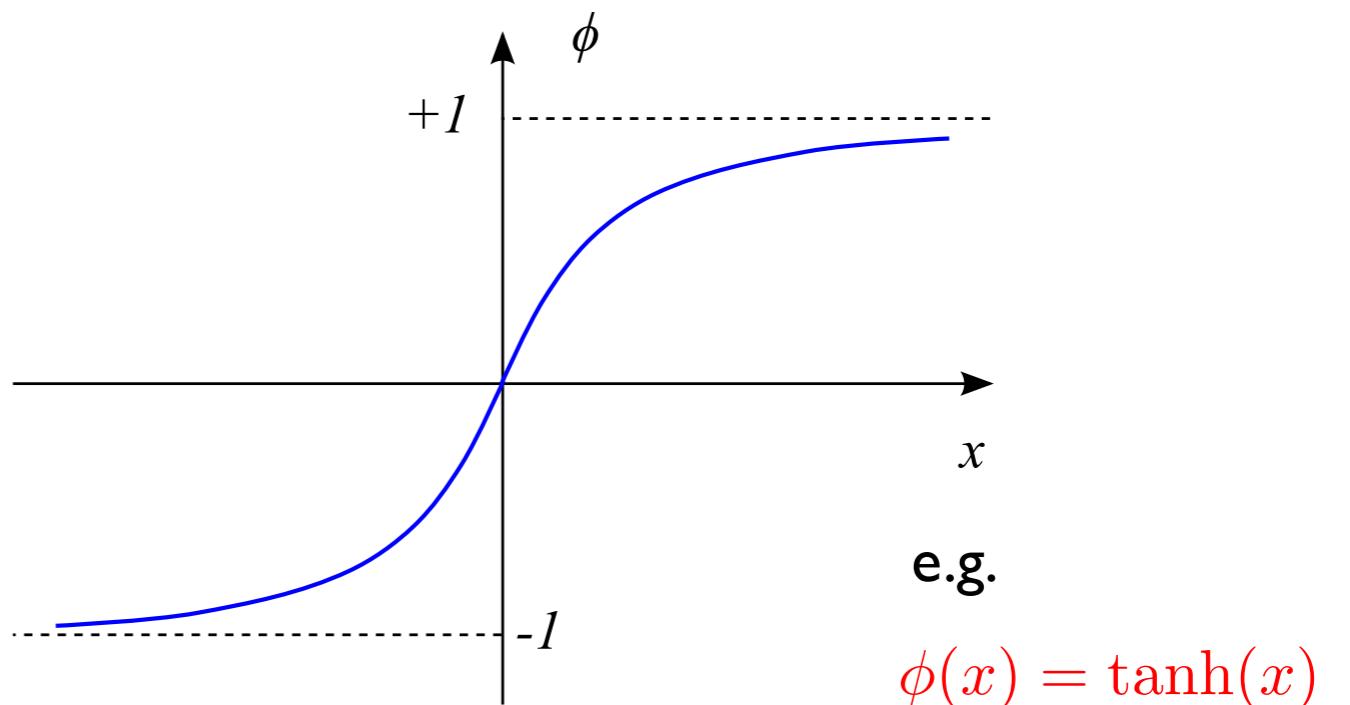
- Spin or “Neuron”

$$S_i(t) = \phi(gh_i(t))$$

$g > 0$ gain parameter

$$\phi(-x) = -\phi(x)$$

$$\phi(\pm\infty) = \pm 1$$



The Model

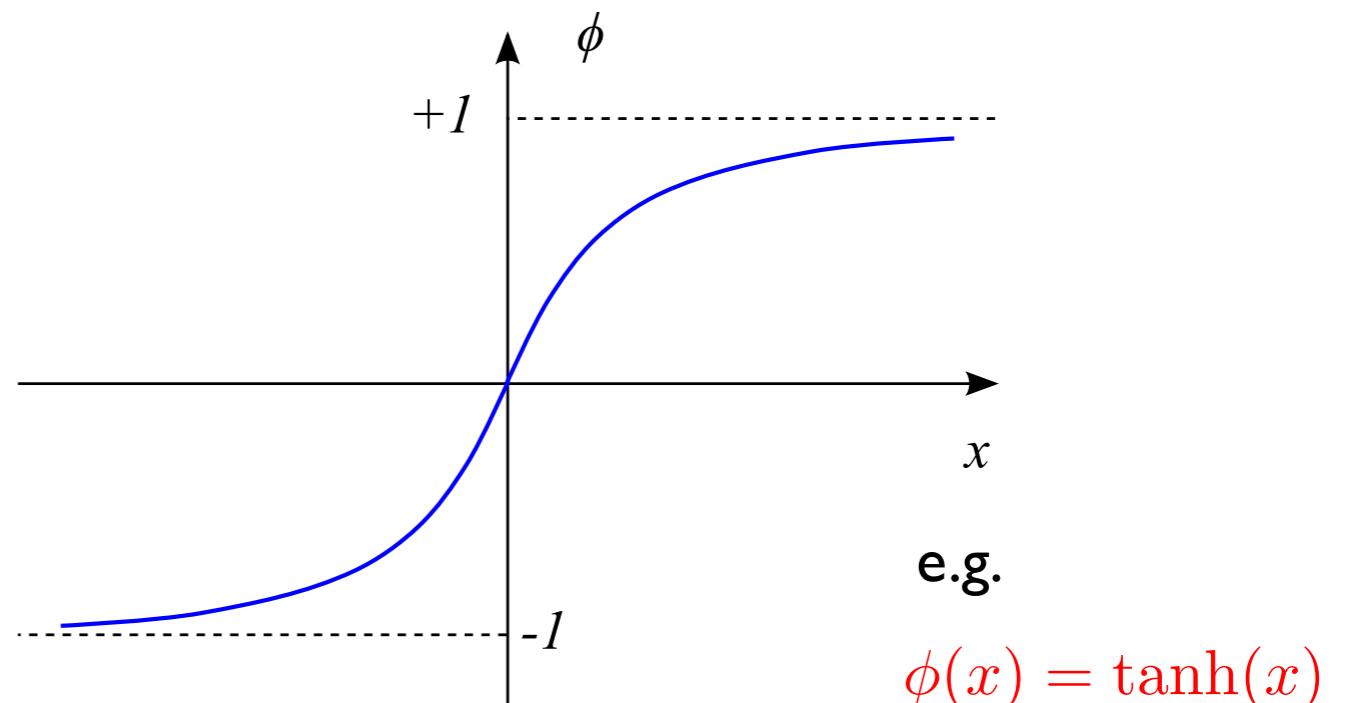
- Spin or “Neuron”

$$S_i(t) = \phi(gh_i(t))$$

$g > 0$ gain parameter

$$\phi(-x) = -\phi(x)$$

$$\phi(\pm\infty) = \pm 1$$



- Dynamics

$$\frac{d}{dt}h_i(t) = -h_i(t) + \sum_{j=1}^N J_{ij} S_j(t) + \rho_i(t)$$

Kirchhoff's Equation

$$h_i(t_0) = h_i^0$$

$J_{ij} :=$ “Synaptic” matrix

External source (field)



$$[J_{ii} = 0]$$

The Model

Our goal is to describe the dynamical behavior of the network

- Dynamics depends on the Synaptic Matrix

- *symmetric* J_{ij}  Relaxation of an Energy Function $E(h_1, \dots, h_n)$
Dynamics is “*simple*”
Stable fix points local minima of Energy
- *non-symmetric* J_{ij}  No Energy Function
Dynamics is *non-trivial*
Fix points, Limit Cycles, Chaotic behaviour

The Model

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• *symmetric* J_{ij}  Relaxation of an Energy Function $E(h_1, \dots, h_n)$

Dynamics is “*simple*”

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• *non-symmetric* J_{ij}  No Energy Function

Dynamics is *non-trivial*

Fix points, Limit Cycles, Chaotic behaviour

- Assumptions

$t_0 \rightarrow -\infty$ Steady state

$N \gg 1$ Large System (Mean Field, Loop Expansion,...)

J_{ij} Random Matrix

Dynamic Field Theory in a Nutshell

Consider:

$$\Rightarrow \partial_a h_i^a = F_i[h^a] + h_i^0 \delta(t_a - t_0)$$

$$F_i[h^a] = -h_i^a + \sum_{j=1}^N J_{ij} S(h_j^a) + \rho_i(t)$$



Initial Condition

Useful notation

$$h_i^a = h_i(t_a)$$
$$\partial_a = \frac{d}{dt_a} + \delta \quad (\delta \rightarrow 0^+)$$

Causality

Correlation functions:

$$\langle h_i^a h_j^b \dots \rangle$$

Average over initial condition, disorder, etc...



Response functions:

$$\frac{\delta}{\delta \rho_k^c} \frac{\delta}{\delta \rho_l^d} \dots \langle h_i^a h_j^b \dots \rangle_\rho$$

(Susceptibilities)

Dynamic Field Theory in a Nutshell

Consider:

$$\Rightarrow \partial_a h_i^a = F_i[h^a] + h_i^0 \delta(t_a - t_0)$$

Useful notation

$$F_i[h^a] = -h_i^a + \sum_{j=1}^N J_{ij} S(h_j^a) + \rho_i(t)$$

$$h_i^a = h_i(t_a)$$
$$\partial_a = \frac{d}{dt_a} + \delta \quad (\delta \rightarrow 0^+)$$

Path Integral Approach



Generating Functional for Correlation and Response Functions induced by the dynamics

Dynamic Field Theory in a Nutshell

- a) Discretize time: dynamical equation \rightarrow finite difference equation

$$\partial_a h_i^a = F_i[h^a] + h_i^0 \delta(t_a - t_0) \quad \Rightarrow \quad h_i^{a+1} - h_i^a = F_i[h^a] \delta t + h_i^0 \delta_{a,0}^{\text{Kr}}$$

Kronecker delta

- b) Generating Functional: sum $e^{i\hat{b}_i^a h_i^a}$ over all path (trajectories)

$$Z[\hat{b}] = \int \prod_{i,a} dh_i^a \delta(h_i^a - \tilde{h}_i^a) e^{i\hat{b}_i^a h_i^a}$$

Solution of the finite difference equation

Dynamic Field Theory in a Nutshell

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$$\partial_a h_i^a = F_i[h^a] + h_i^0 \delta(t_a - t_0) \quad \Rightarrow \quad h_i^{a+1} - h_i^a = F_i[h^a] \delta t + h_i^0 \delta_{a,0}^{\text{Kr}}$$

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Solution of the finite difference equation

• Derivatives $i\hat{b}$ \Rightarrow Products of h \Rightarrow $\hat{b} = 0 \rightarrow$ Correlation Functions

Note: $Z[\hat{b} = 0] = 1$

Dynamic Field Theory in a Nutshell

a) Discretize time: dynamical equation \rightarrow finite difference equation

$$\partial_a h_i^a = F_i[h^a] + h_i^0 \delta(t_a - t_0) \quad \longrightarrow \quad h_i^{a+1} - h_i^a = F_i[h^a] \delta t + h_i^0 \delta_{a,0}^{\text{Kr}}$$

b) Generating Functional: sum $e^{i\hat{b}_i^a h_i^a}$ over all path (trajectories)

$$Z[\hat{b}] = \int \prod_{i,a} dh_i^a \delta(h_i^a - \tilde{h}_i^a) e^{i\hat{b}_i^a h_i^a} \quad \xrightarrow{\hspace{10em}} \text{Solution of the finite difference equation}$$

$$h_i^a - \tilde{h}_i^a = 0 \quad \longrightarrow \quad f(h_i^a) = h_i^{a+1} - h_i^a - F_i[h^a] \delta t - h_i^0 \delta_{a,0}^{\text{Kr}} = 0$$

$$\xrightarrow{\hspace{10em}} \delta(h_i^a - \tilde{h}_i^a) = |f'(h_i^a)| \delta(f(h_i^a)) \quad \text{Ito scheme } \rightarrow \text{Jacobian} = 1$$

\curvearrowleft Jacobian transformation: $h_i^a - \tilde{h}_i^a = 0 \rightarrow f(h_i^a) = 0$

Dynamic Field Theory in a Nutshell

a) Discretize time: dynamical equation \rightarrow finite difference equation

$$\partial_a h_i^a = F_i[h^a] + h_i^0 \delta(t_a - t_0) \quad \Rightarrow \quad h_i^{a+1} - h_i^a = F_i[h^a] \delta t + h_i^0 \delta_{a,0}^{\text{Kr}}$$

b) Generating Functional: sum $e^{i\hat{b}_i^a h_i^a}$ over all path (trajectories)

$$\begin{aligned} Z[\hat{b}] &= \int \prod_{i,a} dh_i^a \delta(h_i^a - \tilde{h}_i^a) e^{i\hat{b}_i^a h_i^a} \\ &= \int \prod_{i,a} dh_i^a \delta(h_i^{a+1} - h_i^a - F_i[h^a] \delta t - h_i^0 \delta_{a,0}^{\text{Kr}}) e^{i\hat{b}_i^a h_i^a} \end{aligned}$$

Solution of the finite difference equation

Dynamic Field Theory in a Nutshell

c) Integral Representation of δ Function: hat-fields

$$\delta(z_i^a) = \int_{-\infty}^{+\infty} \frac{d\hat{h}_i^a}{2\pi} e^{-i\hat{h}_i^a z_i^a}$$

$$\Rightarrow Z[\hat{b}] = \int \prod_{i,a} \frac{d\hat{h}_i^a dh_i^a}{2\pi} \exp \left[-i\hat{h}_i^a \left(h_i^{a+1} - h_i^a - F_i[h_a] \delta t - h_i^0 \delta_{a,0}^{\text{Kr}} \right) + i\hat{b}_i^a h_i^a \right]$$

Dynamic Field Theory in a Nutshell

c) Integral Representation of δ Function: hat-fields

$$\delta(z_i^a) = \int_{-\infty}^{+\infty} \frac{d\hat{h}_i^a}{2\pi} e^{-i\hat{h}_i^a z_i^a}$$

⇒ $Z[\hat{b}] = \int \prod_{i,a} \frac{d\hat{h}_i^a dh_i^a}{2\pi} \exp \left[-i\hat{h}_i^a \left(h_i^{a+1} - h_i^a - F_i[h_a] \delta t - h_i^0 \delta_{a,0}^{\text{Kr}} \right) + i\hat{b}_i^a h_i^a \right]$

d) Add source for hat-field and take continuum limit $\delta t \rightarrow 0$

$$Z[\hat{b}, b] = \int \mathcal{D}\hat{h}_i \mathcal{D}h_i e^{-S[\hat{h}, h] + \sum_{ia} (i\hat{b}_i^a h_i^a + i\hat{h}_i^a b_i^a)}$$

$$S[\hat{h}, h] = \sum_{i,a} i\hat{h}_i^a [\partial_a h_i^a - F_i[h^a] - h_i^0 \delta(t_a - t_0)]$$

$$\mathcal{D}h_i = \lim_{\delta t \rightarrow 0} \prod_a dh_i^a$$

$$\mathcal{D}\hat{h}_i = \lim_{\delta t \rightarrow 0} \prod_a \frac{d\hat{h}_i^a}{2\pi}$$

$$\sum_a = \int_{t_0}^t dt_a$$

Dynamic Field Theory in a Nutshell

- hat-fields \hat{h} → Response fields

$$Z[\hat{b}, b] = \int \mathcal{D}\hat{h}_i \mathcal{D}h_i e^{-S[\hat{h}, h] + \sum_{ia} (i\hat{b}_i^a h_i^a + i\hat{h}_i^a b_i^a)}$$

$$S[\hat{h}, h] = \sum_{i,a} i\hat{h}_i^a [\partial_a h_i^a - F_i[h^a] - h_i^0 \delta(t_a - t_0)]$$

Note: $b_i^a \leftrightarrow \rho_i^a$

Derivatives ρ_i^a → Derivatives b_i^a → Products of $i\hat{h}_i^a$



$$\langle h_{i_1}^{a_1} \dots h_{i_n}^{a_n} \hat{h}_{j_1}^{b_1} \dots \hat{h}_{j_m}^{b_m} \rangle = \frac{\delta}{\delta b_{j_1}^{b_1}} \dots \frac{\delta}{\delta b_{j_m}^{b_m}} \langle h_{i_1}^{a_1} \dots h_{i_n}^{a_n} \rangle$$

Response Functions

Note: $Z[\hat{b} = 0, b] = 1$

Dynamic Field Theory in a Nutshell

- Disorder Average

$$F_i[h^a] = -h_i^a + \sum_{j=1}^N J_{ij} S(h_j^a)$$



→ Correlation/Response functions depend on J_{ij} → Random quantities

Note: $Z[\hat{b} = 0, b] = 1$

Average Correlation/Response →

$$\bar{Z}[\hat{b}, b] = \int d\mathbf{J} P[\mathbf{J}] Z[\hat{b}, b]$$

Dynamic Field Theory in a Nutshell

- General Matrix:


$$J_{ij} = J_{ij}^S + k J_{ij}^A$$
$$J_{ji}^S = J_{ij}^S \quad \text{Symmetric part}$$
$$J_{ji}^A = -J_{ij}^A \quad \text{Antisymmetric part}$$

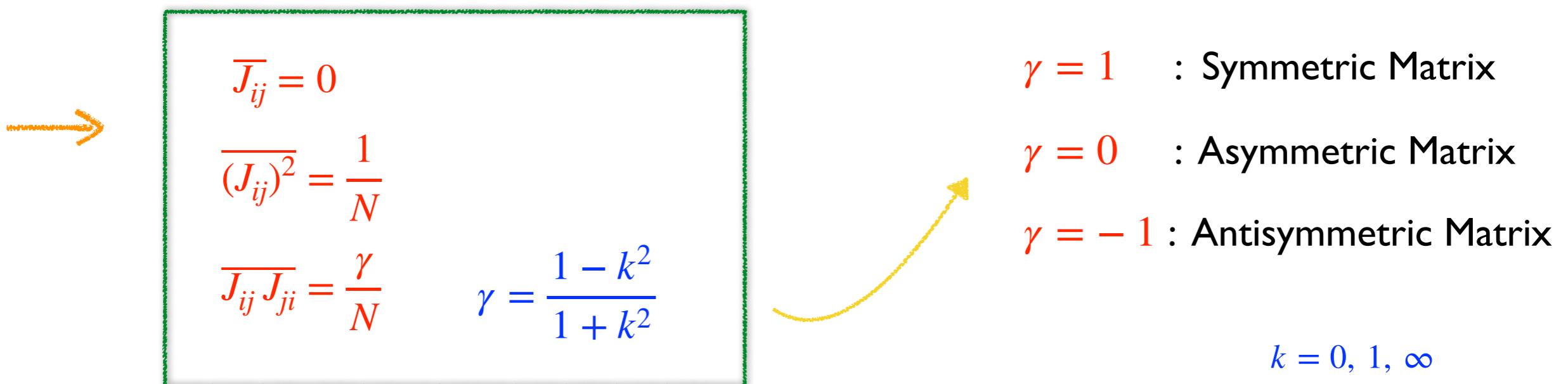
Dynamic Field Theory in a Nutshell

- General Matrix:

$$\boxed{\begin{aligned} J_{ij} &= J_{ij}^S + k J_{ij}^A \\ J_{ji}^S &= J_{ij}^S && \text{Symmetric part} \\ J_{ji}^A &= -J_{ij}^A && \text{Antisymmetric part} \end{aligned}}$$

- i.i.d Gaussian : J_{ij}

$$\overline{J_{ij}^S} = \overline{J_{ij}^A} = 0 \quad \overline{(J_{ij}^S)^2} = \overline{(J_{ij}^A)^2} = \frac{1}{N} \frac{1}{1+k^2}$$



Dynamic Field Theory in a Nutshell

- Disorder Average

$$\bar{Z}[\hat{b}, b] \Rightarrow \overline{\exp \left[\sum_{aij} i \hat{h}_i^a J_{ij} S_j^a \right]}$$

$$\int \frac{dx}{\sqrt{2\pi\sigma^2}} e^{-\frac{x^2}{2\sigma^2} \pm \mu x} = e^{\frac{\sigma^2\mu^2}{2}}$$

Just in case...

Dynamic Field Theory in a Nutshell

- Disorder Average

$$\bar{Z}[\hat{b}, b] \Rightarrow \overline{\exp \left[\sum_{aij} i \hat{h}_i^a J_{ij} S_i^a \right]}$$

$$\begin{aligned} \bar{Z}[\hat{b}, b] = & \int \mathcal{D}h \mathcal{D}\hat{h} \exp \left\{ - \sum_{ia} i \hat{h}_i^a (1 + \partial_a) h_i^a \right. \\ & + \frac{1}{2N} \sum_{ij} \left[\sum_a i \hat{h}_i^a S_j^a \right]^2 + \frac{\gamma}{2N} \sum_{ij} \left[\sum_a i \hat{h}_i^a S_j^a \right] \left[\sum_a i \hat{h}_j^a S_i^a \right] \\ & \left. + \sum_{ia} [i \hat{h}_i^a b_i^a + i \hat{b}_i^a h_i^a] \right\} \end{aligned}$$

Averaged Correlation/Response G.F.

Dynamic Field Theory in a Nutshell

- Disorder Average

$$\bar{Z}[\hat{b}, b] \Rightarrow \overline{\exp \left[\sum_{aij} i \hat{h}_i^a J_{ij} S_i^a \right]}$$

Deterministic part

$$\begin{aligned} \bar{Z}[\hat{b}, b] = \int \mathcal{D}h \mathcal{D}\hat{h} \exp & \left\{ - \sum_{ia} i \hat{h}_i^a (1 + \delta_a) h_i^a \right. \\ & + \frac{1}{2N} \sum_{ij} \left[\sum_a i \hat{h}_i^a S_j^a \right]^2 + \frac{\gamma}{2N} \sum_{ij} \left[\sum_a i \hat{h}_i^a S_j^a \right] \left[\sum_a i \hat{h}_j^a S_i^a \right] \\ & \left. + \sum_{ia} [i \hat{h}_i^a b_i^a + i \hat{b}_i^a h_i^a] \right\} \end{aligned}$$

Averaged Correlation/Response G.F.

Disorder induced interactions → non-local in space and time

Dynamic Field Theory in a Nutshell

- Space Diagonalization

Define: $C^{ab} = \frac{1}{N} \sum_i S_i^a S_i^b$ $G^{ab} = \frac{1}{N} \sum_i S_i^a i \hat{h}_i^b$

Use:
$$\begin{aligned} 1 &= \int \mathcal{D}X^{ab} \delta \left(X^{ab} - \frac{1}{N} \sum_i x^a y^b \right) \\ &= \int \mathcal{D}X^{ab} \mathcal{D}(N \hat{X}^{ab}) \exp \left[-i \hat{X}^{ab} \left(NX^{ab} - \sum_i x^a y^b \right) \right] \end{aligned}$$

Dynamic Field Theory in a Nutshell

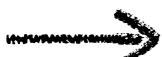
- Space Diagonalization

$$\bar{Z}[\hat{b}, b] = \int \mathcal{D}\hat{C} \mathcal{D}C \mathcal{D}\hat{G} \mathcal{D}G e^{-N\mathcal{S}[\hat{C}, C, \hat{G}, G; \hat{b}, b]} \quad [\text{Exact DFT}]$$

$$\mathcal{S}[\hat{C}, C, \hat{G}, G; \hat{b}, b] = \frac{1}{2} \sum_{ab} \left[i\hat{C}^{ab} C^{ab} + i\hat{G}^{ab} G^{ab} \right] - W[\hat{C}, C, \hat{G}, G; \hat{b}, b]$$

$$W[(\cdot)] = \ln \int \mathcal{D}\hat{h} \mathcal{D}h e^{L[\hat{h}, h; \hat{C}, C, \hat{G}, G, \hat{b}, b]}$$

$$\begin{aligned} L[(\cdot)] = & - \sum_a i\hat{h}^a (1 + \partial_a) h^a \\ & + \frac{1}{2} \sum_{ab} \left[i\hat{C}^{ab} S^a S^b + C^{ab} i\hat{h}^a i\hat{h}^b \right] + \frac{1}{2} \sum_{ab} \left[i\hat{G}^{ab} S^a i\hat{h}^b + \gamma G^{ab} i\hat{h}^a S^b \right] \\ & + \sum_a \left[i\hat{h}^a b^a + i\hat{b}^a h^a \right] \end{aligned}$$



One Variable dynamics

Dynamic Field Theory in a Nutshell

- Consider

$$\begin{aligned}\sum_i \overline{\langle S_i^a S_i^b \rangle} &= \int \prod_i \mathcal{D}\hat{h}_i \mathcal{D}h_i e^{-S[\hat{h}, h]} \sum_i S_i^a S_i^b \\ &= \int \mathcal{D}\hat{C} \mathcal{D}C \mathcal{D}\hat{G} \mathcal{D}G e^{-N\mathcal{S}[\hat{C}, C, \hat{G}, G; 0, 0]} \sum_i S_i^a S_i^b\end{aligned}$$

Dynamic Field Theory in a Nutshell

- Consider

$$\sum_i \overline{\langle S_i^a S_i^b \rangle} = \int \prod_i \mathcal{D}\hat{h}_i \mathcal{D}h_i e^{-S[\hat{h}, h]} \sum_i S_i^a S_i^b$$

$$= \int \mathcal{D}\hat{C} \mathcal{D}C \mathcal{D}\hat{G} \mathcal{D}G e^{-N\mathcal{S}[\hat{C}, C, \hat{G}, G; 0, 0]} \sum_i S_i^a S_i^b$$

But....

$$e^{-N\mathcal{S}[(\cdot)]} \left[\sum_i S_i^a S_i^b \right] \rightarrow e^{-\frac{N}{2} \sum_{ab} i\hat{C}^{ab} C^{ab} + \dots} \int \prod_i \mathcal{D}\hat{h}_i \mathcal{D}h_i e^{\frac{1}{2} \sum_{ab} i\hat{C}^{ab} \sum_i S_i^a S_i^b + \dots} \left[\sum_i S_i^a S_i^b \right]$$

$$\rightarrow e^{-\frac{N}{2} \sum_{ab} i\hat{C}^{ab} C^{ab} + \dots} \left[\frac{\delta}{\delta i\hat{C}^{ab}} \int \prod_i \mathcal{D}\hat{h}_i \mathcal{D}h_i e^{\frac{1}{2} \sum_{ab} i\hat{C}^{ab} \sum_i S_i^a S_i^b + \dots} \right]$$

$$\rightarrow \left[\frac{\delta}{\delta i\hat{C}^{ab}} + NC^{ab} \right] e^{-N\mathcal{S}[(\cdot)]}$$

$$\frac{\delta}{\delta i\hat{C}^{ab}} e^{-\frac{N}{2} \sum_{ab} i\hat{C}^{ab} C^{ab}} = -NC^{ab}$$

Dynamic Field Theory in a Nutshell

- Consider

$$\begin{aligned}
 \sum_i \overline{\langle S_i^a S_i^b \rangle} &= \int \prod_i \mathcal{D}\hat{h}_i \mathcal{D}h_i e^{-S[\hat{h}, h]} \sum_i S_i^a S_i^b \\
 &= \int \mathcal{D}\hat{C} \mathcal{D}C \mathcal{D}\hat{G} \mathcal{D}G e^{-N\mathcal{S}[\hat{C}, C, \hat{G}, G; 0, 0]} \sum_i S_i^a S_i^b \\
 &= \int \mathcal{D}\hat{C} \mathcal{D}C \mathcal{D}\hat{G} \mathcal{D}G \left[\frac{\delta}{\delta i \hat{C}^{ab}} + NC^{ab} \right] e^{-N\mathcal{S}[\hat{C}, C, \hat{G}, G; 0, 0]}
 \end{aligned}$$

↗ *surface term*

$$\boxed{\frac{1}{N} \sum_i \overline{\langle S_i^a S_i^b \rangle} = \int \mathcal{D}\hat{C} \mathcal{D}C \mathcal{D}\hat{G} \mathcal{D}G e^{-N\mathcal{S}[\hat{C}, C, \hat{G}, G; 0, 0]} C^{ab} = \langle C^{ab} \rangle}$$

Average in the $[\hat{C}, C, \hat{G}, G]$ - Field Theory

Mean Field Limit $N \gg 1$

- In the $N \gg 1$ we can use peak integration \mapsto saddle point

$$\bar{Z}[\hat{b}, b] = \int \mathcal{D}\hat{C} \mathcal{D}C \mathcal{D}\hat{G} \mathcal{D}G e^{-N\mathcal{S}[\hat{C}, C, \hat{G}, G; \hat{b}, b]} \sim e^{-N\mathcal{S}_0[\hat{C}, C, \hat{G}, G; \hat{b}, b]} \quad N \gg 1$$

where $\{\hat{C}, C, \hat{G}, H\}$ follows from the stationary point:

$$\frac{\delta}{\delta i\hat{C}^{ab}} \mathcal{S}[(\cdot)] = 0 \quad \Rightarrow \quad C^{ab} = \langle S^a S^b \rangle_0 \quad \text{Self-consistent equations}$$

$$\frac{\delta}{\delta C^{ab}} \mathcal{S}[(\cdot)] = 0 \quad \Rightarrow \quad i\hat{C}^{ab} = \langle i\hat{h}^a i\hat{h}^b \rangle_0 = 0$$

$$\frac{\delta}{\delta i\hat{G}^{ab}} \mathcal{S}[(\cdot)] = 0 \quad \Rightarrow \quad G^{ab} = \langle S^a i\hat{h}^b \rangle_0$$

$$\frac{\delta}{\delta G^{ab}} \mathcal{S}[(\cdot)] = 0 \quad \Rightarrow \quad i\hat{G}^{ab} = \gamma \langle i\hat{h}^a S^b \rangle_0 = \gamma G^{ba}$$

Mean Field Limit $N \gg 1$

- In the $N \gg 1$ we can use peak integration \mapsto saddle point

$$\bar{Z}[\hat{b}, b] \sim \bar{Z}^{(sp)}[\hat{b}, b] = \left[\int \mathcal{D}\hat{h} \mathcal{D}h e^{-L[\hat{h}, h; (\cdot)_0]} \right]^N \quad N \gg 1$$

$$L[\hat{h}, h; (\cdot)_0] = - \sum_a i\hat{h}^a \left[(1 + \partial_a) h^a - \gamma \sum_b G^{ab} S^b - b^a \right] + \frac{1}{2} \sum_{ab} C^{ab} i\hat{h}^a i\hat{h}^b$$

*Self-consistent dynamics
of one variable*

Mean Field Limit $N \gg 1$

- In the $N \gg 1$ limit the dynamics can be reduced to a **self-consistent** dynamics of a **single variables**

$$\bar{Z}[\hat{b}, b] \sim \bar{Z}^{(sp)}[\hat{b}, b] = \left[\int \mathcal{D}\hat{h} \mathcal{D}h e^{-L[\hat{h}, h; (\cdot)_0]} \right]^N \quad N \gg 1$$

$$L[\hat{h}, h; (\cdot)_0] = - \sum_a i\hat{h}^a \left[(1 + \partial_a) h^a - \gamma \sum_b G^{ab} S^b - b^a \right] + \frac{1}{2} \sum_{ab} C^{ab} i\hat{h}^a i\hat{h}^b$$

Use:

$$e^{\frac{1}{2} \sum_{ab} i\hat{h}^a C^{ab} i\hat{h}^b} = \left\langle e^{\sum_a i\hat{h}^a \eta^a} \right\rangle_\eta$$

η Gaussian field with

$$\langle \eta^a \eta^b \rangle_\eta = C^{ab}$$

$$\langle \eta^a \rangle_\eta = 0$$

*Self-consistent dynamics
of one variable*



$$\int \mathcal{D}\hat{h} \mathcal{D}h e^{-\sum_a i\hat{h}^a [\dots] + \frac{1}{2} \sum_{ab} C^{ab} i\hat{h}^a i\hat{h}^b} = \left\langle \int \mathcal{D}\hat{h} \mathcal{D}h e^{-\sum_a i\hat{h}^a [\dots - \eta^a]} \right\rangle_\eta$$

Mean Field Limit $N \gg 1$

- In the $N \gg 1$ limit the dynamics can be reduced to a **self-consistent** dynamics of a **single variables**

→ $\partial_a h^a = -h^a + \gamma \sum_b G^{ab} S^b + b^a + \eta^a + h^0 \delta(t_a - t_0)$
 η zero-mean Gaussian field with $\langle \eta^a \eta^b \rangle = C^{ab}$

*Stochastic dynamics
of one variable*

Note:

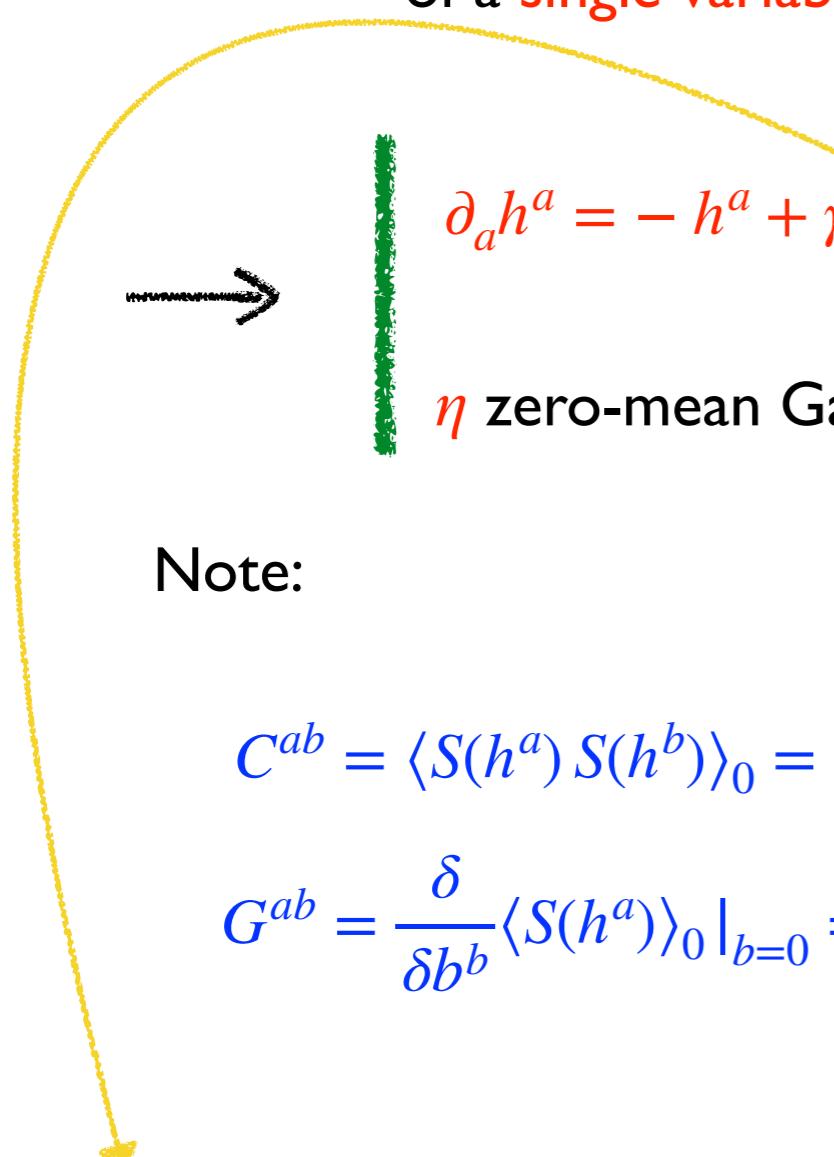
$$C^{ab} = \langle S(h^a) S(h^b) \rangle_0 = \frac{1}{N} \sum_i \overline{\langle S^a S^b \rangle}$$

Self-Consistent Equation

$$G^{ab} = \frac{\delta}{\delta b^b} \langle S(h^a) \rangle_0 |_{b=0} = \frac{1}{N} \sum_i \frac{\delta}{\delta b^b} \overline{\langle S^a \rangle} |_{b=0}$$

Mean Field Limit $N \gg 1$

- In the $N \gg 1$ limit the dynamics can be reduced to a **self-consistent** dynamics of a **single variables**


$$\partial_a h^a = -h^a + \gamma \sum_b G^{ab} S^b + b^a + \eta^a + h^0 \delta(t_a - t_0)$$

η zero-mean Gaussian field with $\langle \eta^a \eta^b \rangle = C^{ab}$

*Stochastic dynamics
of one variable*

Note:

$$C^{ab} = \langle S(h^a) S(h^b) \rangle_0 = \frac{1}{N} \sum_i \overline{\langle S^a S^b \rangle}$$
$$G^{ab} = \frac{\delta}{\delta b^b} \langle S(h^a) \rangle_0 |_{b=0} = \frac{1}{N} \sum_i \frac{\delta}{\delta b^b} \overline{\langle S^a \rangle} |_{b=0}$$

Self-Consistent Equation



From now on : $\gamma = 0$

→ Fully Asymmetric Matrix

Feed-back from **symmetric** component
of synaptic matrix J_{ij}

Self-Consistent Dynamics


$$\partial_a h^a = -h^a + \eta^a$$

$\eta^a :=$ Gaussian field of zero mean and correlation $\langle \eta^a \eta^b \rangle_\eta = C^{ab}$

Where:

$$C^{ab} = \langle S^a S^b \rangle_0 = \frac{1}{N} \sum_i \overline{\langle S_i(t_a) S_i(t_b) \rangle}$$



Self-Consistent Equation

$$C(t) = \langle S(t+t_0) S(t_0) \rangle = \langle \phi(gh(t+t_0)) \phi(gh(t_0)) \rangle$$

$$h(t) = \int_{-\infty}^t ds e^{-(t-s)} \eta(s)$$

Linear function of η

Differential Self-Consistent Equation

Define

$$\Delta^{ab} = \langle h(t_a) h(t_b) \rangle \equiv \langle h^a h^b \rangle \quad \text{field-field correlation function}$$

Self-Consistent dynamics

$$(1 + \partial_a) h^a = \eta^a \longrightarrow (1 + \partial_a)(1 + \partial_b) \langle h^a h^b \rangle = \langle \eta^a \eta^b \rangle$$

Taking $t = t_a - t_b$ leads to the differential self-consistent equation



$$\boxed{\Delta(t) - \partial_t^2 \Delta(t) = C(t)}$$

Closed Equation

$$C(t) \equiv C(\Delta(t))$$

Correlation

$$C^{ab} = \langle S^a S^b \rangle = \langle \phi(gh^a) \phi(gh^b) \rangle$$

Fourier Transform

$$\phi(x) = \int_{-\infty}^{+\infty} \frac{dk}{2\pi} \tilde{\phi}(k) e^{-ikx}$$

$$\longrightarrow C^{ab} = \int \frac{dk}{2\pi} \frac{dk'}{2\pi} \tilde{\phi}(k) \tilde{\phi}(k') \left\langle e^{-ikgh^a - ik'gh^b} \right\rangle_\eta$$

$h[\eta]$ linear function of η \longrightarrow h Gaussian Field with $\langle h^a \rangle = 0$, $\langle h^a h^b \rangle = \Delta^{ab}$

$$C^{ab} = \int \frac{dk}{2\pi} \frac{dk'}{2\pi} \tilde{\phi}(k) \tilde{\phi}(k') \exp \left\{ -\frac{g^2}{2} [\Delta_0(k^2 + k'^2) + 2\Delta k k'] \right\}$$

where

$$\Delta^{aa} = \Delta^{bb} = \Delta_0 \quad \Delta^{ab} = \Delta$$

Self-Consistent Newton Equation

Since $C^{ab} \equiv C(\Delta; \Delta_0)$

$$\partial_t^2 \Delta = \Delta - C \equiv -\partial_\Delta V(\Delta; \Delta_0)$$

Newton Equation

→ $V(\Delta; \Delta_0) = -\frac{\Delta^2}{2} + \int_0^\Delta d\Delta' C(\Delta'; \Delta_0)$

Classical 1D motion

Classical Motion with Energy $E_c = \frac{1}{2}(\partial_t \Delta)^2 + V(\Delta; \Delta_0)$

Boundary Conditions

a) $\Delta(t)$ Autocorrelation function



$$|\Delta(t)| \leq \Delta(t=0) = \Delta_0$$

Bounded Classical Orbits

b) $\Delta(t) = \frac{1}{2} \int_{-\infty}^{+\infty} dt' e^{-|t-t'|} C(t')$



Differentiable even function of t



$$\Delta(-t) = \Delta(t)$$

$$\partial_t \Delta(t)|_{t=0} = 0$$

c) $\Delta(t=0) = \Delta_0$ free → *Different solutions with different classical energy* $E_c = V(\Delta_0; \Delta_0)$

Classical Potential

Noticing:

$$\int_0^\Delta d\Delta' C(\Delta'; \Delta_0) = -\frac{1}{g^2} \int \frac{dk}{2\pi k} \frac{dk'}{2\pi k'} \tilde{\phi}(k) \tilde{\phi}(k') \exp \left\{ -\frac{g^2}{2} [\Delta_0(k^2 + k'^2) + 2\Delta' k k'] \right\} \Big|_0^\Delta$$

Defining:

$$\Phi(x) = \int_0^x dy \phi(y) \quad \tilde{\Phi}(k) \Rightarrow \tilde{\phi}(k)/k$$

e.g.

$$\phi(x) = \tanh(x) \Rightarrow \Phi(x) = \ln \cos(x)$$



$$V(\Delta; \Delta_0) = -\frac{\Delta^2}{2} + \frac{1}{g^2} \int Dz \left[\int Dx \Phi(gx\sqrt{\Delta_0 - |\Delta|} + gz\sqrt{|\Delta|}) \right]^2 - \frac{1}{g^2} \left[\int Dx \Phi(gx\sqrt{\Delta_0}) \right]^2$$

where: $Dx = \frac{dx}{\sqrt{2\pi}} e^{-x^2/2}$ Gaussian Measure

Solutions

$$*) \quad \frac{\partial^3}{\partial \Delta^3} V(\Delta; \Delta_0) = g^4 \int Dz \left[\int Dx \phi'' \left(gx\sqrt{\Delta_0 - |\Delta|} + gz\sqrt{|\Delta|} \right) \right]^2 > 0$$

$\longrightarrow \frac{\partial^2}{\partial \Delta^2} V(\Delta; \Delta_0)$ monotonously increasing function of $|\Delta|$
 has **no** zero or has **one** zero for $0 < \Delta < \Delta_0$

$$*) \quad V(\Delta; \Delta_0) = \left[-1 + g^2 [\phi']_{\Delta_0}^2 \right] \frac{\Delta^2}{2} + O(\Delta^4) \quad |\Delta| \ll 1$$

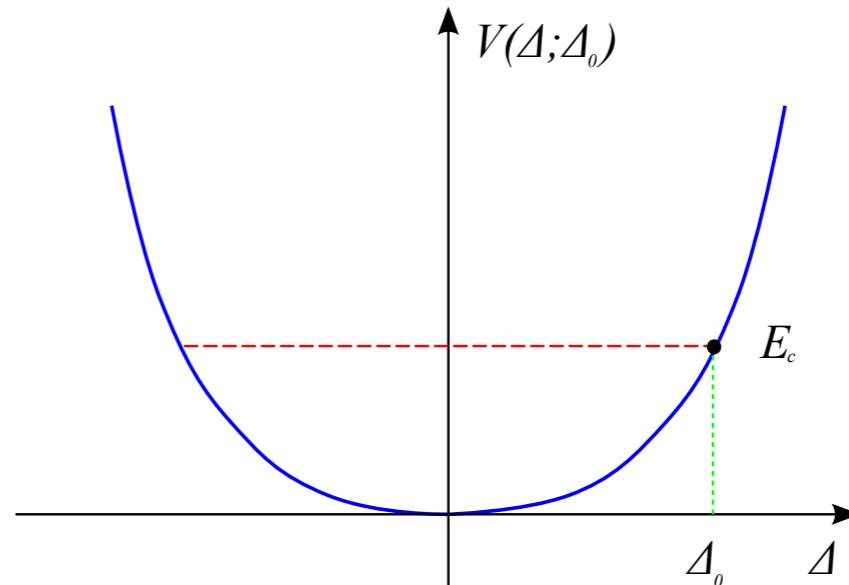
$$[f]_{\Delta_0} = \int Dx f(gx\sqrt{\Delta_0})$$

Cases:

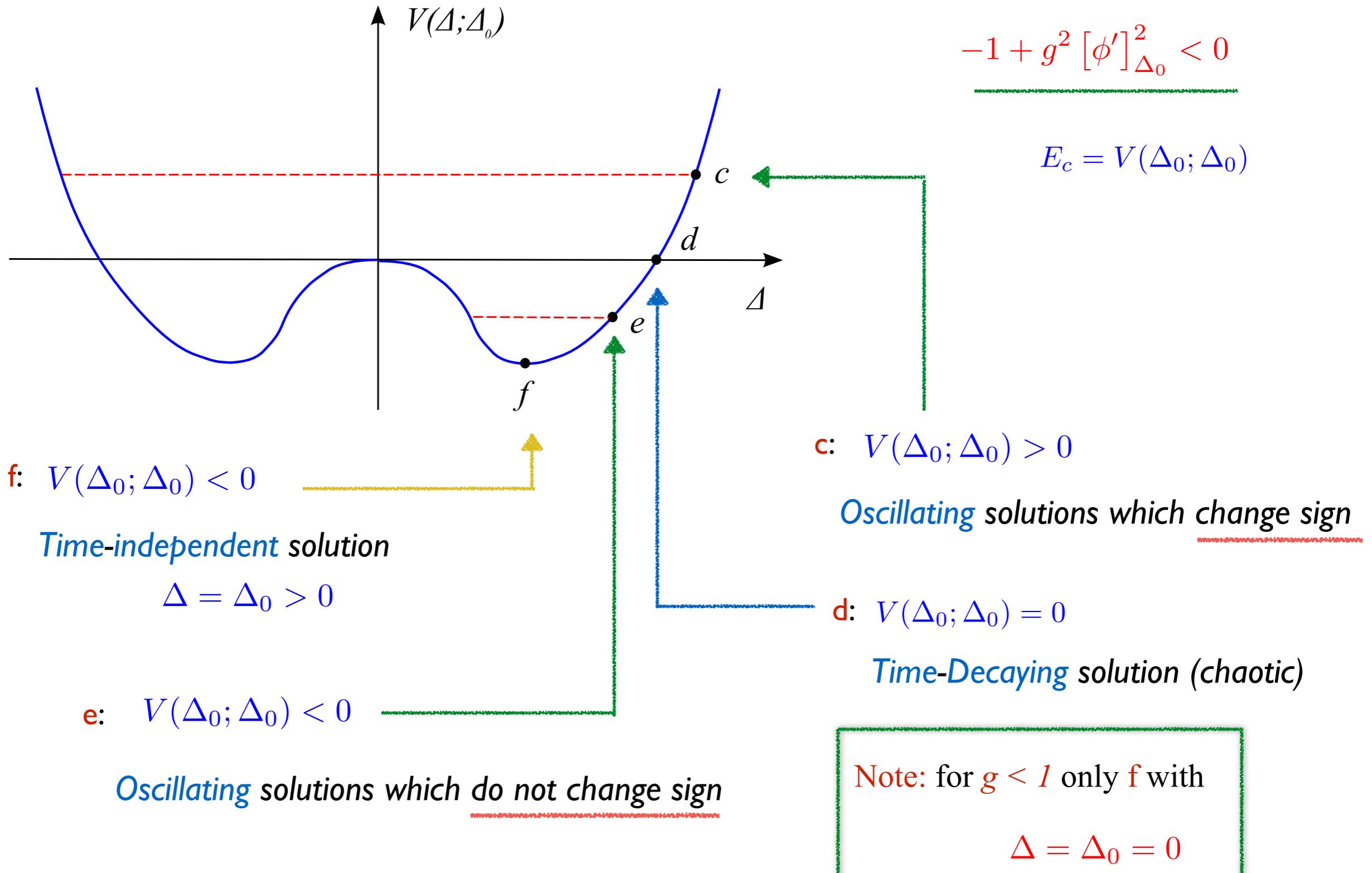
a: $-1 + g^2 [\phi']_{\Delta_0}^2 > 0$

$$E_c = V(\Delta_0; \Delta_0) > 0$$

Oscillating solutions which changes sign



Solutions



Phase diagram

→ $g < 1$

Time-Independent solution

$$\Delta = \Delta_0 = 0$$

→ $g > 1$

f: Time-Independent solution with

$$\Delta = \Delta_0 = q > 0$$

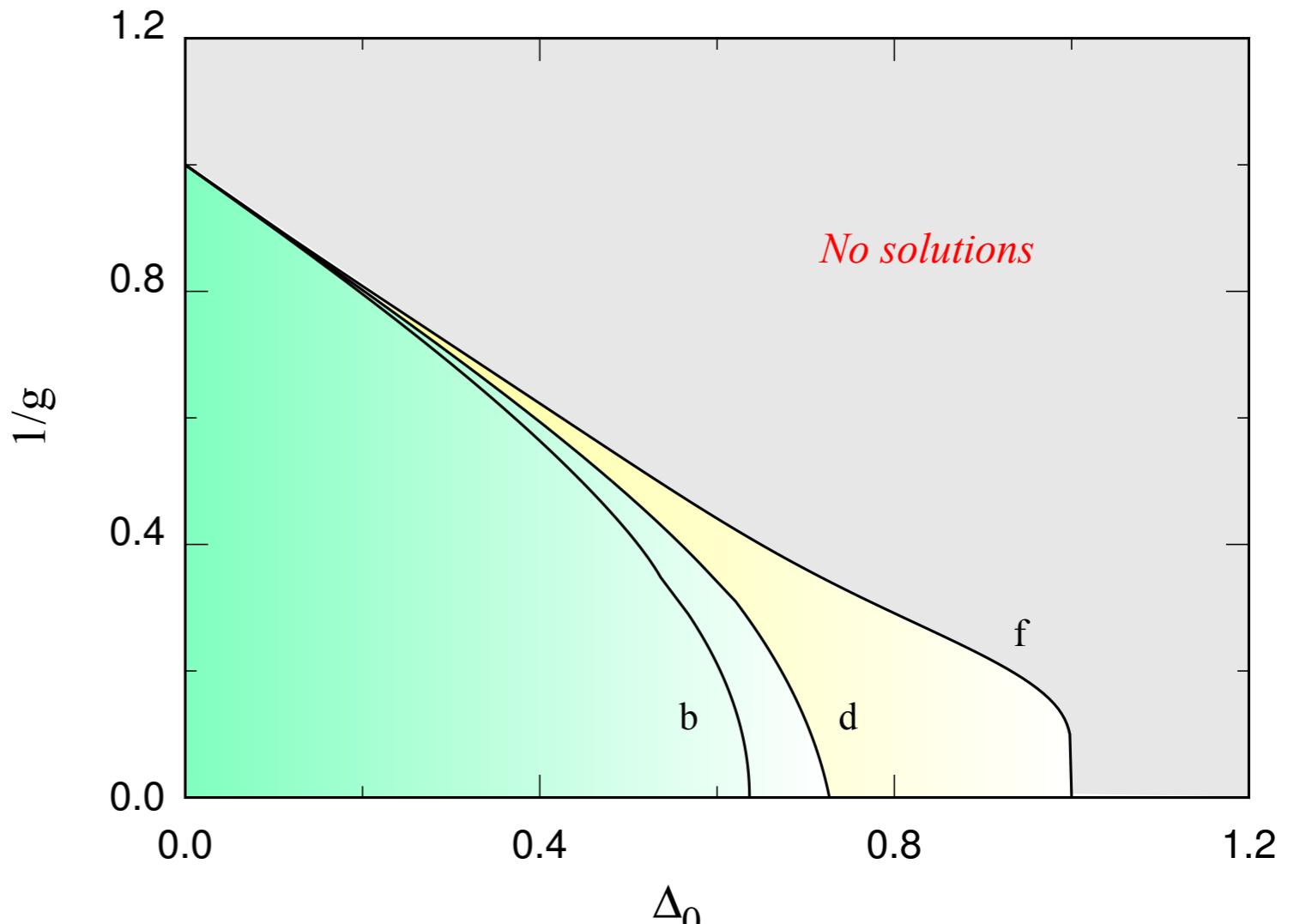
$$q = [\phi^2]_q = \int Dz \phi^2(gz\sqrt{q})$$

(SK Solution)

f:- d: Oscillating solution which do not change sign

d: Time-decaying solution: $\lim_{t \rightarrow \infty} \Delta(t) = 0$

Below d: Oscillating solutions which change sign



b) $-1 + g^2 [\phi']_{\Delta_0}^2 = 0$
single / double well

Stability Mean Field Limit

→ Replicas: $S^a \equiv S^a(t_a), \quad a = 1, \dots, n$

$$\begin{aligned} \overline{Z}[\rho, \hat{\rho}] &= \int \mathcal{D}C \mathcal{D}\hat{C} e^{-N\mathcal{S}[C, \hat{C}; \rho, \hat{\rho}]} \\ \mathcal{S}[C, \hat{C}; \rho, \hat{\rho}] &= \frac{1}{2} \sum_{ab} i\hat{C}^{ab} C^{ab} - W[C, \hat{C}; \rho, \hat{\rho}] \end{aligned} \quad (\text{recall...})$$

$$\begin{aligned} W[C, \hat{C}; \rho, \hat{\rho}] &= \ln \int \mathcal{D}h \mathcal{D}\hat{h} e^{L(h, \hat{h}; C, \hat{C}, \rho, \hat{\rho})} \\ L(h, \hat{h}; C, \hat{C}, \rho, \hat{\rho}) &= - \sum_a i\hat{h}^a (1 + \partial_a) h^a + \frac{1}{2} \sum_{ab} \left[i\hat{C}^{ab} S^a S^b + C^{ab} i\hat{h}^a i\hat{h}^b \right] \\ &\quad + \sum_a \left[i\hat{h}^a \rho^a + i\hat{\rho}^a h^a \right] \end{aligned}$$

→ Fluctuations:

$$C = C^{(sp)} + Q \quad i\hat{C} = i\hat{C}^{(sp)} + i\hat{Q}$$

$$\begin{aligned} \overline{Z}[\rho, \hat{\rho}] &\sim \overline{Z}^{(sp)}[\rho, \hat{\rho}] \int \mathcal{D}Q \mathcal{D}\hat{Q} e^{-N\mathcal{S}_2[Q, \hat{Q}; \rho, \hat{\rho}]} \\ \mathcal{S}_2[Q, \hat{Q}; \rho, \hat{\rho}] &= \frac{1}{2} \sum_{ab} i\hat{Q}^{ab} Q^{ab} - \frac{1}{4} \sum_{ab, cd} i\hat{Q}^{ab} \langle S^a S^b i\hat{h}^c i\hat{h}^d \rangle Q^{cd} \\ &\quad - \frac{1}{8} \sum_{ab, cd} i\hat{Q}^{ab} \left[\langle S^a S^b S^c S^d \rangle - \langle S^a S^b \rangle \langle S^c S^d \rangle \right] i\hat{Q}^{cd} \end{aligned}$$

Stability Mean Field Limit

To evaluate $\langle S^a S^b i\hat{h}^c i\hat{h}^d \rangle$

Define: $(1 + \partial_a)(1 + \partial_b)\Psi^{ab} = Q^{ab}$

$$\rightarrow \mathcal{S}_2[\Psi, \hat{Q}; \rho, \hat{\rho}] = \frac{1}{8} \sum_{ab,cd} i\hat{Q}^{ab} [\langle S^a S^b S^c S^d \rangle - \langle S^a S^b \rangle \langle S^c S^d \rangle] i\hat{Q}^{cd} + \frac{1}{2} \sum_{ab} i\hat{Q}^{ab} \mathcal{A}\Psi^{ab}$$

$$\mathcal{A}\Psi^{ab} = (1 + \partial_a)(1 + \partial_b)\Psi^{ab} - \frac{\partial}{\partial \Delta^{ab}} \langle S^a S^b \rangle \Psi^{ab} - \frac{\partial}{\partial \Delta^{aa}} \langle S^a S^b \rangle \Psi^{aa} - \frac{\partial}{\partial \Delta^{bb}} \langle S^a S^b \rangle \Psi^{bb}$$

\hat{Q} -integration $\rightarrow \int \mathcal{D}\Psi \exp[-(\dots)\Psi \mathcal{A}^\dagger \mathcal{A}\Psi]$

Stability Condition:

$$\mathcal{A}\Psi^{ab} = \Lambda \Psi^{ab}, \quad \Lambda \neq 0$$

Useful Relations

Define:

$$\xi = x\sqrt{\Delta_0 - |\Delta|} + z\sqrt{|\Delta|}$$

→ $\frac{\partial}{\partial \Delta^{ab}} \langle S^a S^b \rangle = g^2 \int Dz \left[\int Dx \phi'(g \xi) \right]^2$

→ $\frac{\partial}{\partial \Delta^{aa}} \langle S^a S^b \rangle = \frac{g^2}{2} \int Dz \left[\int Dx \phi''(g \xi) \right] \left[\int Dx \phi(g \xi) \right]$

Stability: Time-Independent Solution

Stability Equation:

$$\left[(1 + \partial_a)(1 + \partial_b) - g^2 [(\phi')^2]_q \right] \Psi^{ab} - \frac{g^2}{2} [\phi \phi'']_q (\Psi^{aa} + \Psi^{bb}) = \Lambda \Psi^{ab}$$

$$\Delta = \Delta_0 = q$$

Case $g < 1$

$$q = 0 \longrightarrow \phi(0) = \phi''(0) = 0, \quad \phi'(0) = 1$$

Set $t_a - t_b = t$

Fourier Transform $\tilde{f}(\omega) = \int dt e^{i\omega t} f(t)$

$$\longrightarrow 1 + \omega^2 - g^2 = \Lambda \quad \text{Stability Equation}$$

$\boxed{\Lambda > 0 \quad \text{for all } \omega}$

$\longrightarrow \Delta = \Delta_0 = 0 \quad \text{Stable for } g < 1$

Stability: Time-Independent Solution

Case $g > 1$ $q = [\phi^2]_q > 0$

Fluctuations $\Psi^{ba} = \Psi^{ab}$

Symmetric

$$\Psi^{ab}(t_a, t_b) = \Psi_S(t_a, t_b)$$

$$\Psi_S(t_b, t_a) = \Psi_S(t_a, t_b)$$

Anti-Symmetric

$$\Psi^{ab}(t_a, t_b) = \epsilon^{ab} \Psi_A(t_a, t_b)$$

$$\Psi_A(t_b, t_a) = -\Psi_A(t_a, t_b)$$

$$\epsilon^{ba} = -\epsilon^{ab}$$

Set $t_a - t_b = t$

$$\Rightarrow 1 + \omega^2 - g^2[(\phi')^2]_q = \Lambda \quad \text{Relevant Eigenvalue}$$

But $1 - g^2[(\phi')^2]_q < 0$ [de Almeida Thouless]

$\exists \omega$ such that $\Lambda = 0$

$\Rightarrow \Delta = \Delta_0 = q > 0$ unstable for $g > 1$

Stability: Time-Dependent Solutions

Stability Equation:

$$\left[\partial_a + \partial_b + \partial_a \partial_b - \frac{\partial^2}{\partial \Delta^2} V(\Delta; \Delta_0) \right] \Psi^{ab} - \frac{1}{2} \frac{\partial^2}{\partial \Delta_0 \partial \Delta} V(\Delta; \Delta_0) [\Psi^{aa} + \Psi^{bb}] = \Lambda \Psi^{ab}$$

Critical Fluctuations

$$\Psi^{aa} = 0, \quad \Psi^{ab} = \Psi(t_a - t_b) \quad \text{off-diagonal replica fluctuations}$$

Set $\partial_a \equiv \delta + \partial_{t_a}$ [$\delta \rightarrow 0^+$] to ensure causality

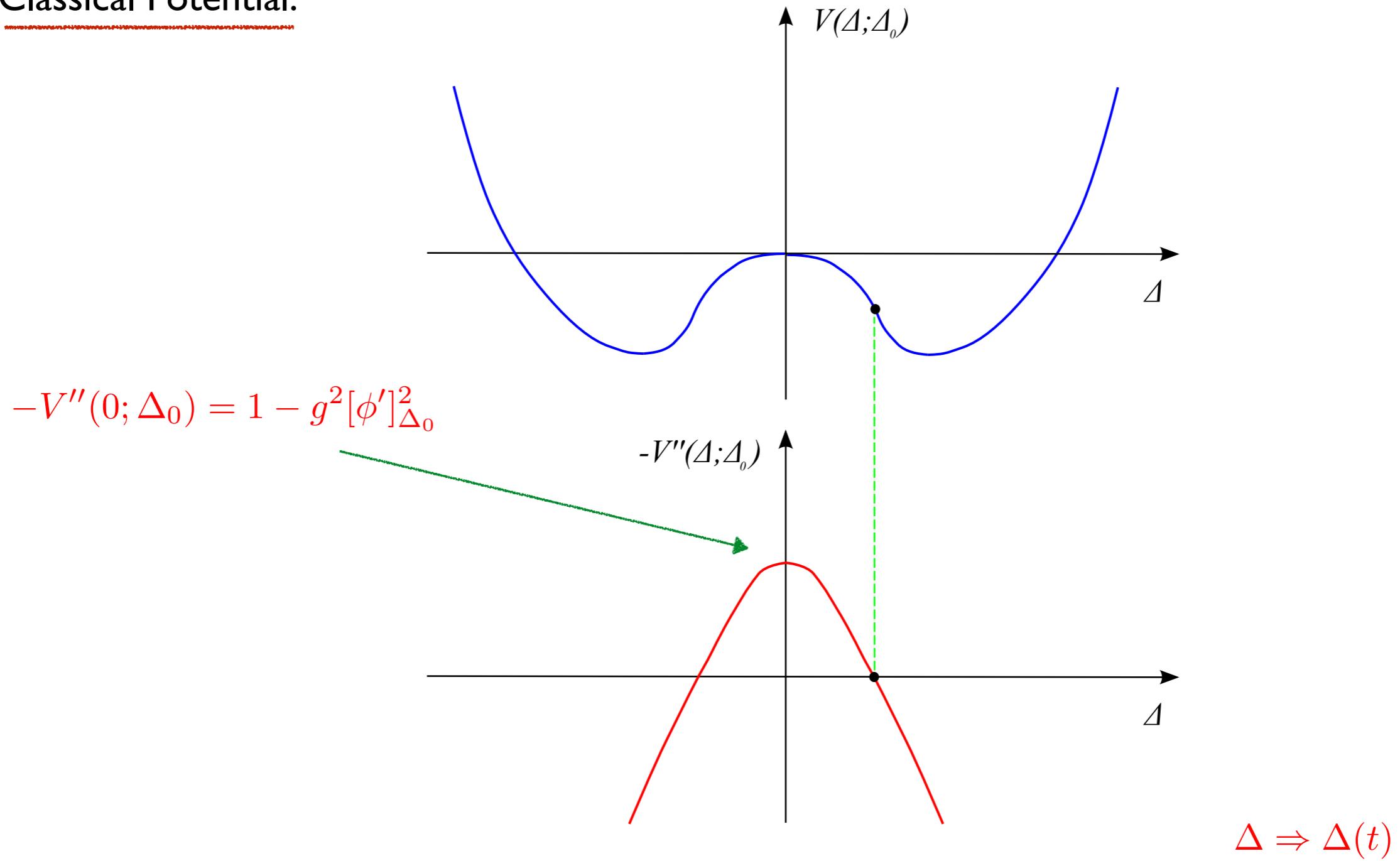
$$\Rightarrow \left[-\partial_t^2 - \partial_\Delta^2 V(\Delta; \Delta_0) \right] \Psi(t) = \epsilon \Psi(t) \quad \text{Stability Equation}$$

$$\Lambda = 2\delta + \epsilon \quad \text{1D Schrödinger Equation}$$

$$V_{\text{QM}}(t) = - \partial_\Delta^2 V(\Delta; \Delta_0) \Big|_{\Delta=\Delta(t)}$$

Stability: Time-Dependent Solutions

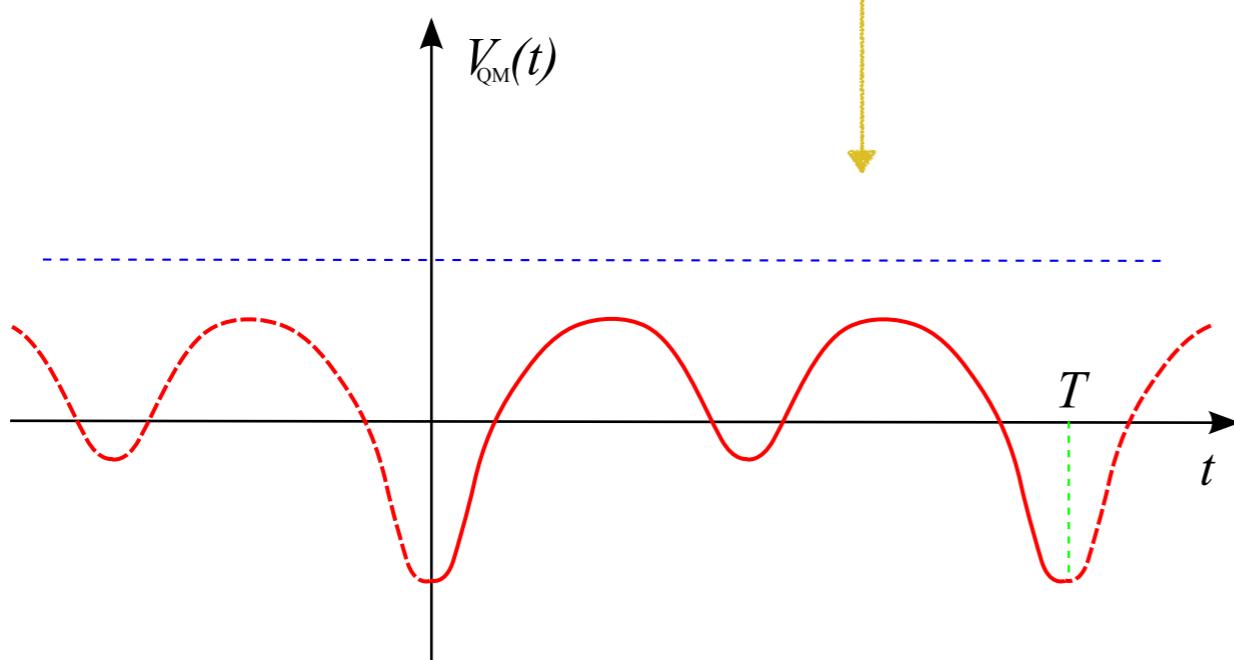
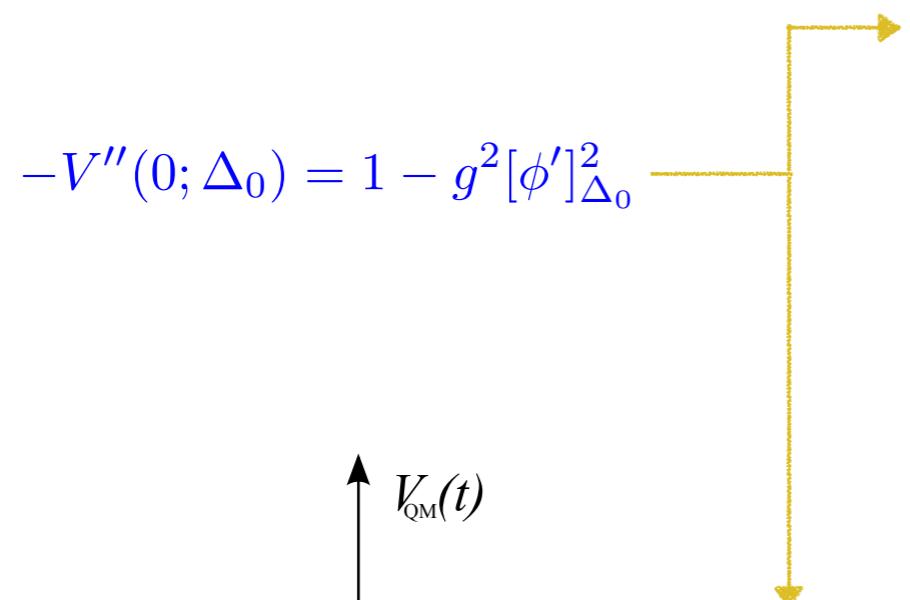
Classical Potential:



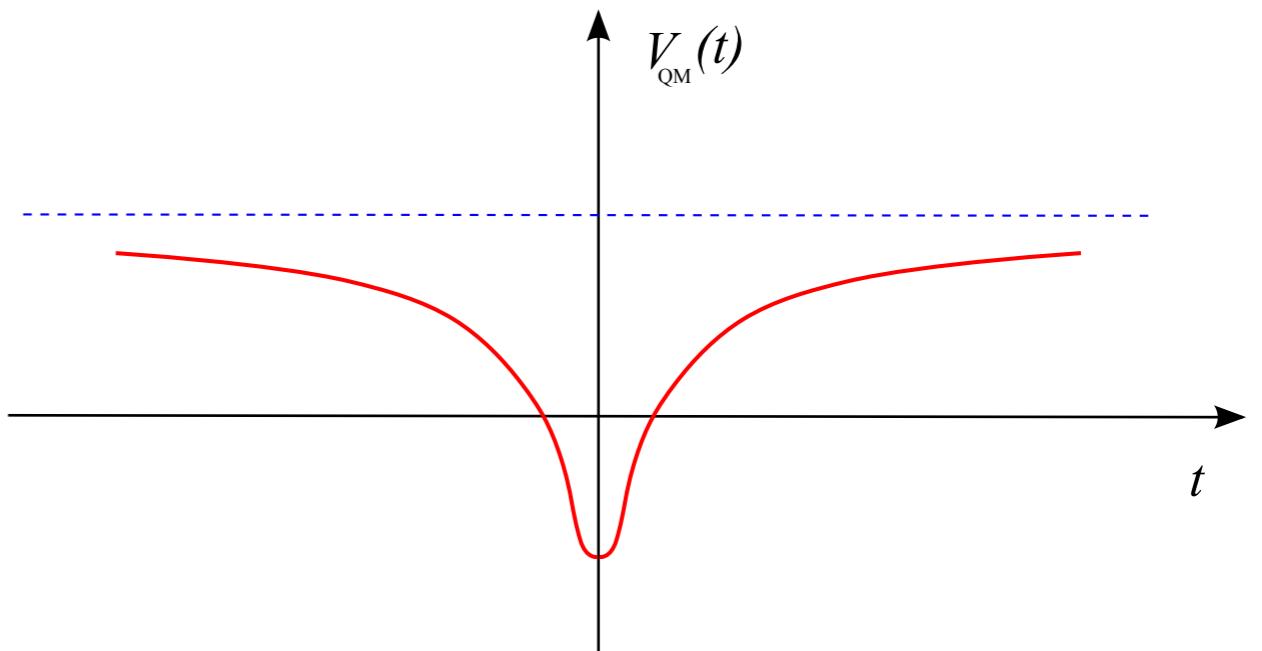
Stability: Time-Dependent Solutions

Quantum Mechanical Potential:

$$V_{QM}(t) = -\partial_{\Delta}^2 V(\Delta; \Delta_0) \Big|_{\Delta=\Delta(t)}$$



Time-Periodic solution



Time-Decaying solution

Stability: Time-Dependent Solutions

Self-Consistent Equation:

$$\partial_t^2 \Delta = -\partial_\Delta V(\Delta; \Delta_0) \implies [-\partial_t^2 - \partial_\Delta^2 V(\Delta; \Delta_0)] \partial_t \Delta = 0$$

$$\partial_t \Delta \text{ eigenvector with eigenvalue } \epsilon = 0 \implies \Lambda = 2\delta$$

marginally stable $\delta \rightarrow 0^+$

Time-Decaying solution:

$$\Psi(0) = \partial_t \Delta(t)|_{t=0} = 0 \implies \Psi = \partial_t \Delta \text{ has exactly one node}$$

There is exactly one eigenfunction with eigenvalue $\epsilon_0 < 0$

$$\boxed{\Lambda = \epsilon_0 + 2\delta \neq 0} \implies \underline{\text{stable}}$$

Stability: Time-Dependent Solutions

Time-Periodic solution:

$\Psi(t)$ periodic solution of period $T \longrightarrow \Psi = \partial_t \Delta$ changes sign *once* in a period T and vanishes at $t = 0, T$

There is exactly one periodic eigenfunction with eigenvalue $\epsilon_0 < 0$

But....

Periodic potential \longrightarrow Energy bands

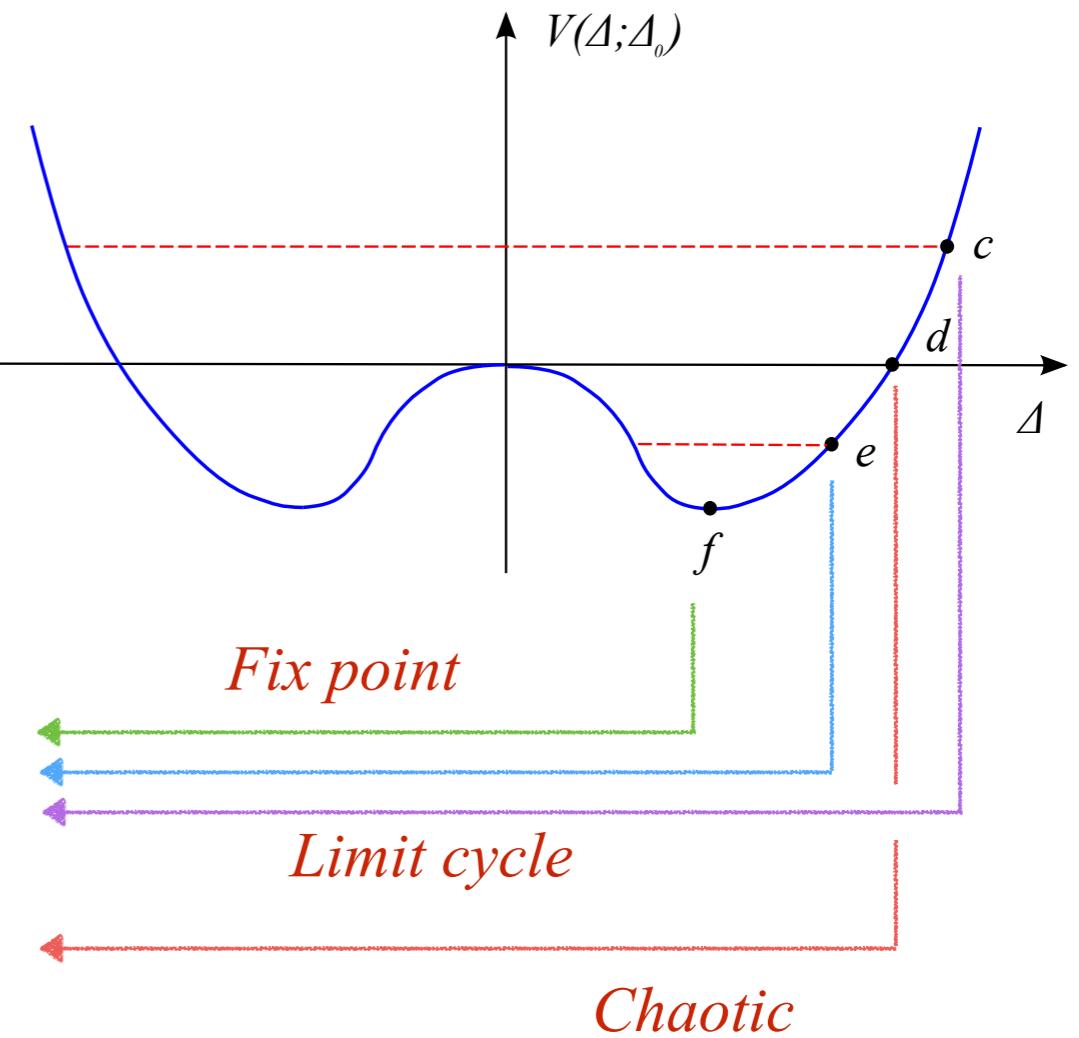
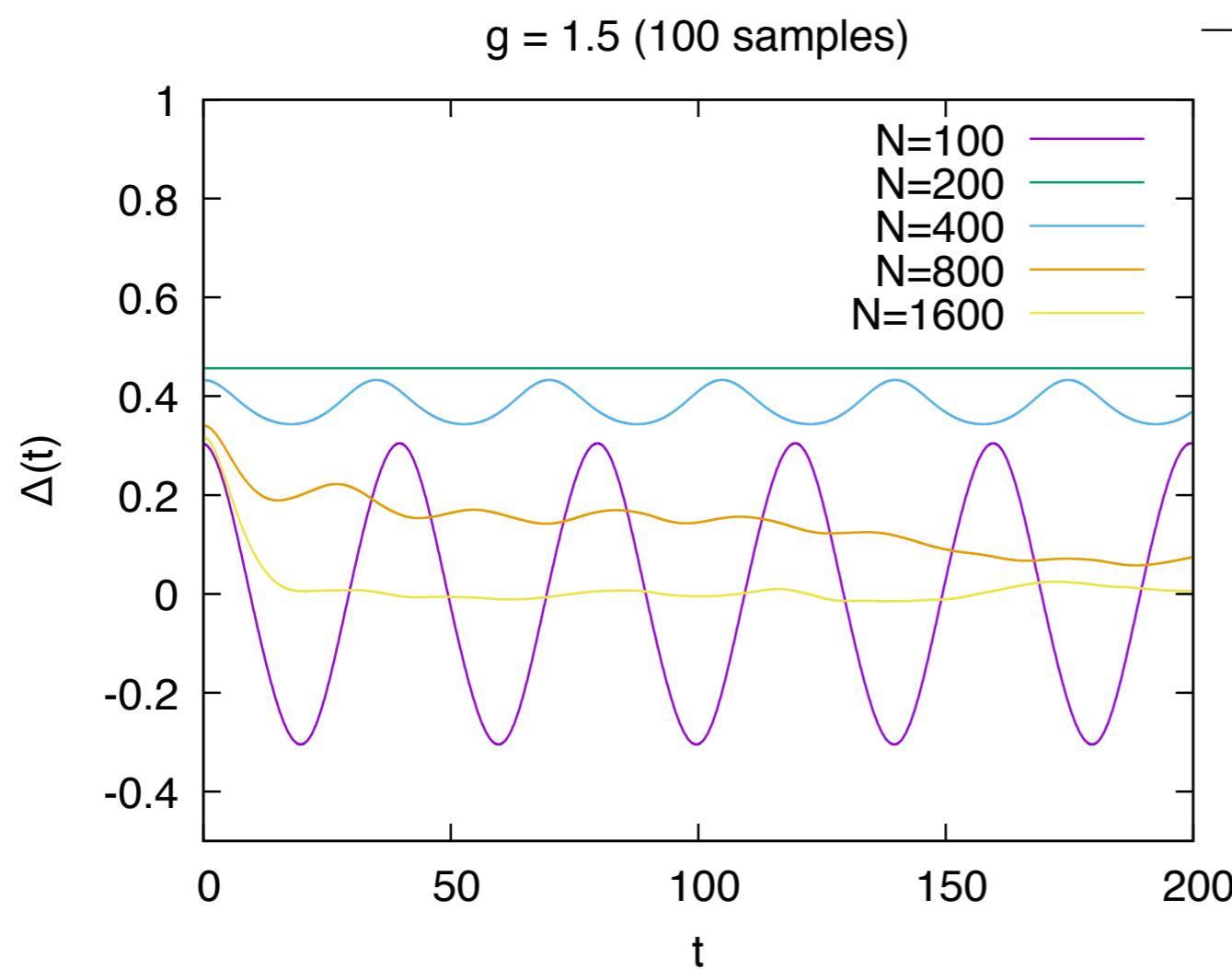
$\epsilon_0 < 0$ bottom of lowest energy bands

Λ passes *continuously* through 0

\longrightarrow unstable

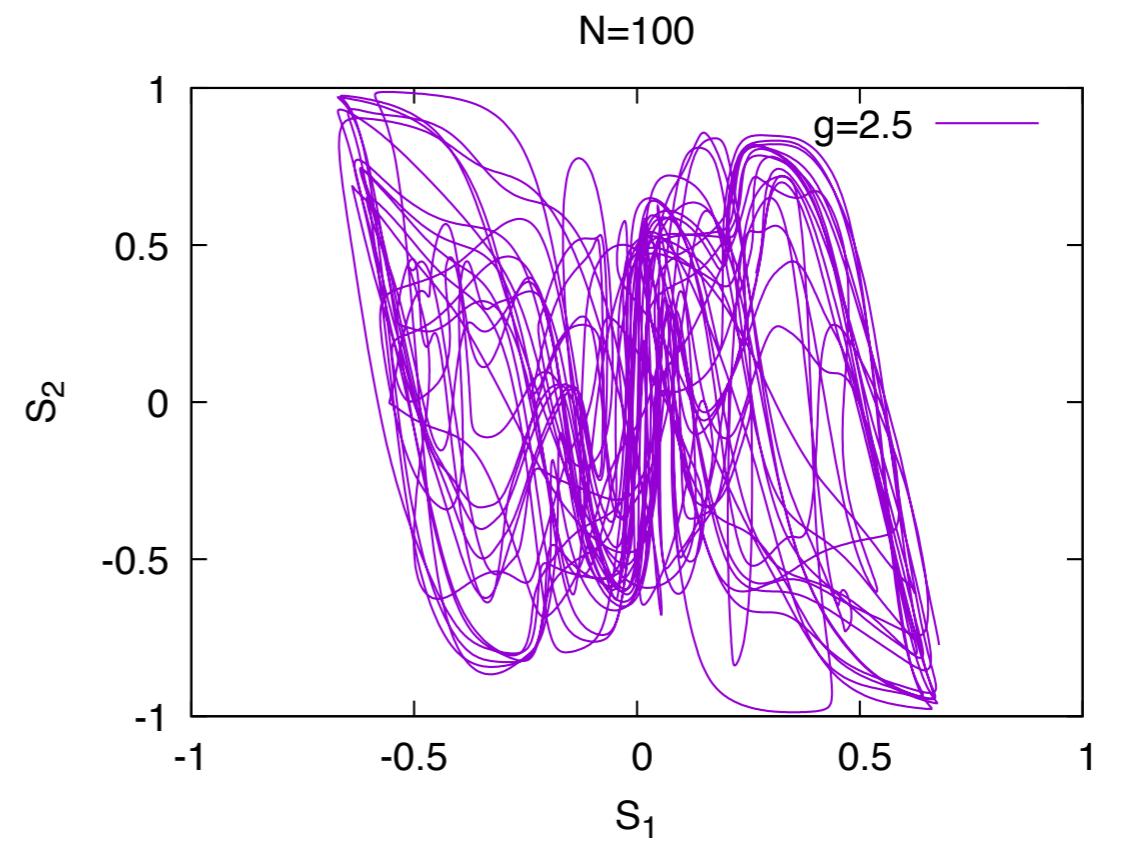
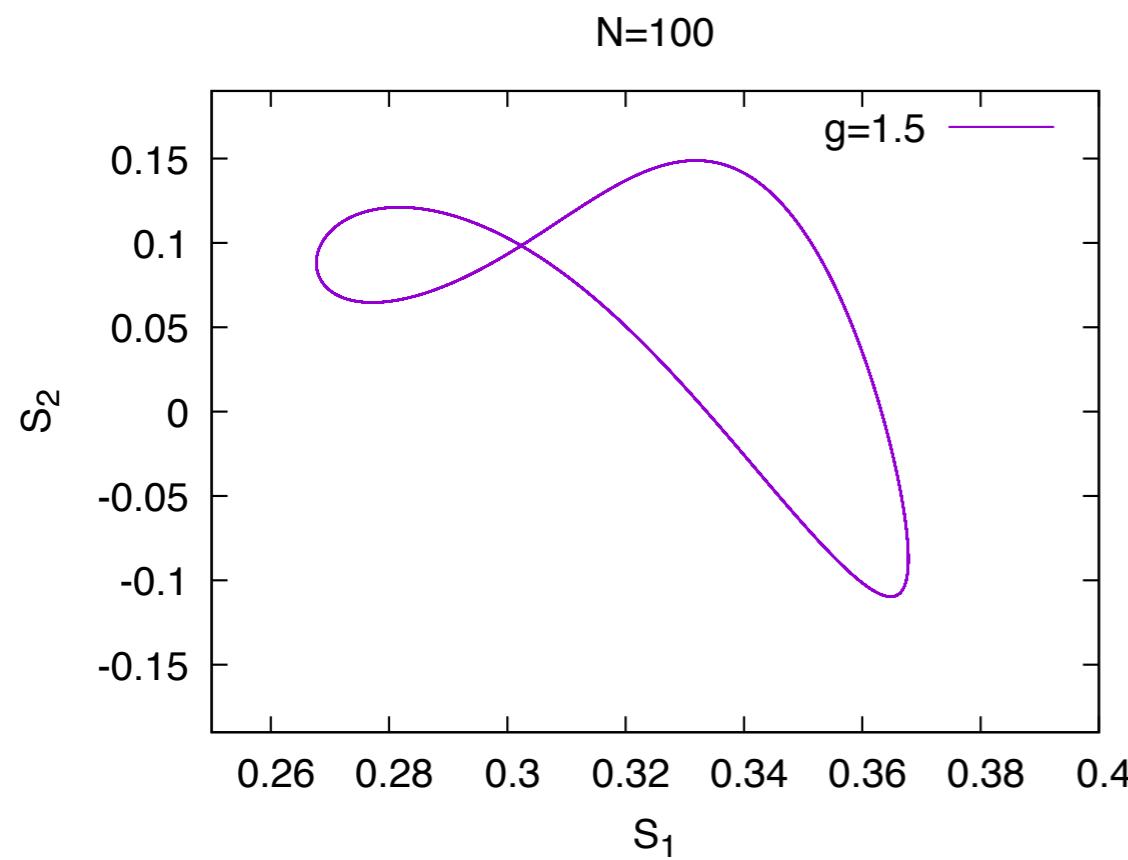
Some Numerical Result

→ Fixed g :



Some Numerical Result

→ Fixed N :

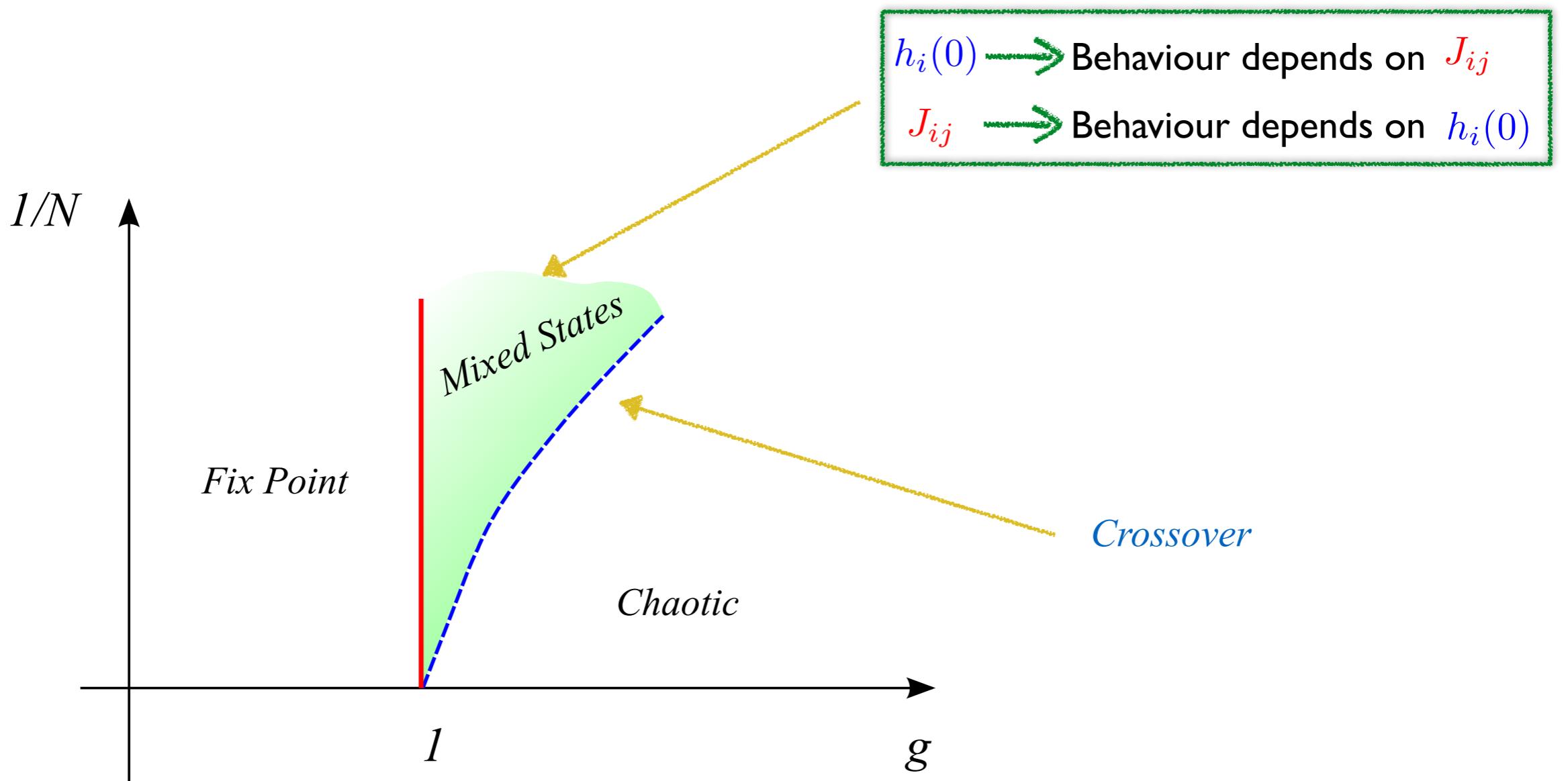


Chaotic behaviour

Periodic behaviour

Some Numerical Result

Finite N \rightarrow Smooth transition Fix Point / Chaotic



Maximal Lyapunov Exponent

Lyapunov Exponent controls the **growth** of **small** perturbations

$$h_i(t=0) \rightarrow h_i(t=0) + \delta h_i(0)$$

$$\longrightarrow |\delta h(t)| \sim |\delta h(0)| e^{\lambda t}, \quad t \gg 1$$

$\lambda :=$ *Lyapunov Exponent*

$\lambda > 0$ *Chaotic Behaviour*

How do we compute λ

*) Perturbation evolution law:

$$\partial_t \delta h_i = -\delta h_i + g \sum_{j=1}^N J_{ij} \phi'(gh_j) \delta h_j \quad \text{Linearised equation of motion}$$

$$\longrightarrow \delta h_i(t) = \sum_{j=1}^N \tilde{\chi}_{ij}(t, t_0) \delta h_j(t_0)$$

$$\tilde{\chi}_{ij}(t, t_0) = \left. \frac{\delta h_i(t)}{\delta h_j(t_0)} \right|_{h_j=0}$$

Maximal Lyapunov Exponent

*) Perturbation growth:

$$\frac{1}{N} \sum_{i=1}^N \delta h_i(t)^2 = \sum_{jk} A_{jk}(t, t_0) \delta h_j(t_0) \delta h_k(t_0)$$

$$A_{jk}(t, t_0) = \frac{1}{N} \sum_{i=1}^N \tilde{\chi}_{ij}(t, t_0) \tilde{\chi}_{ik}(t, t_0) \quad \text{symmetric matrix}$$

*) Lyapunov Exponent:

$$\frac{1}{N} \sum_{i=1}^N \delta h_i(t)^2 \sim e^{2\lambda t}, \quad t \gg 1$$

$$\Rightarrow \boxed{\lambda = \lim_{t \rightarrow \infty} \frac{1}{2t} \ln [\text{Tr } A(t, t_0)] = \lim_{t \rightarrow \infty} \frac{1}{2t} \ln \left[\frac{1}{N} \sum_{ij} \tilde{\chi}_{ij}(t, t_0)^2 \right]}$$

$N \gg 1$ self-averaging

Maximal Lyapunov Exponent

*) Spin Susceptibility:

$$\chi_{ij}(t, t_0) = \left. \frac{\delta S_i(t)}{\delta h_j(t_0)} \right|_{h_j=0} = g\phi'(gh_i) \tilde{\chi}_{ij}(t, t_0)$$
$$\rightarrow \lambda = \lim_{t \rightarrow \infty} \frac{1}{2t} \ln \left[\frac{1}{N} \sum_{ij} \chi_{ij}(t, t_0)^2 \right]$$

*) Dynamic Field Theory:

$$\chi_{ij}(t, t_0) \rightarrow \langle S_i(t) i\hat{h}_j(t_0) \rangle$$

replicas

$$\rightarrow \frac{1}{N} \sum_{ij} \chi_{ij}(t, t_0)^2 \rightarrow \frac{1}{N} \sum_{ij} \langle S_i^a S_i^b i\hat{h}_j^c i\hat{h}_j^d \rangle \quad a = c \neq b = d \quad \textit{replica indexes}$$

Maximal Lyapunov Exponent

$$\rightarrow \boxed{\frac{1}{N} \sum_{ij} \langle S_i^a S_i^b i\hat{h}_j^c i\hat{h}_j^d \rangle = N \langle C^{ab} i\hat{C}^{cd} \rangle - \frac{1}{2N} [\delta_{ac}\delta_{bd} + \delta_{ad}\delta_{bc}]} \quad \text{green box}$$

$\langle C^{ab} i\hat{C}^{cd} \rangle$ two-point correlation function of the theory governed by the action $N\mathcal{S}[C, \hat{C}; 0, 0]$

where:

$$\mathcal{S}[C, \hat{C}; 0, 0] = \frac{1}{2} \sum_{ab} i\hat{C}^{ab} C^{ab} - W[C, \hat{C}; 0, 0]$$

$$W[C, \hat{C}; 0, 0] = \ln \int \mathcal{D}h \mathcal{D}\hat{h} e^{L(h, \hat{h}; C, \hat{C}, 0, 0)} \quad \text{dynamic single-site field theory}$$

$$L(h, \hat{h}; C, \hat{C}, 0, 0) = - \sum_a i\hat{h}^a (1 + \partial_a) h^a + \frac{1}{2} \sum_{ab} [i\hat{C}^{ab} S^a S^b + C^{ab} i\hat{h}^a i\hat{h}^b]$$

Maximal Lyapunov Exponent $N \gg 1$

Saddle point

$$\mathcal{S}[C, \hat{C}] \sim \mathcal{S}^{(sp)}[C, 0] + \mathcal{S}_2[Q, \hat{Q}], \quad N \gg 1$$

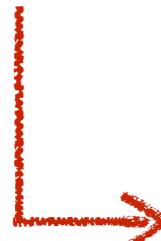
where: (see *fluctuations*)

$$\mathcal{S}_2[\Psi, \hat{Q}] = \frac{1}{8} \sum_{ab,cd} i\hat{Q}^{ab} \left[\langle S^a S^b S^c S^d \rangle - \langle S^a S^b \rangle \langle S^c S^d \rangle \right] i\hat{Q}^{cd} + \frac{1}{2} \sum_{ab} i\hat{Q}^{ab} \mathcal{A}\Psi^{ab}$$

$$\mathcal{A}\Psi^{ab} = (1 + \partial_a)(1 + \partial_b)\Psi^{ab} - \frac{\partial}{\partial \Delta^{ab}} \langle S^a S^b \rangle \Psi^{ab} - \frac{\partial}{\partial \Delta^{aa}} \langle S^a S^b \rangle \Psi^{aa} - \frac{\partial}{\partial \Delta^{bb}} \langle S^a S^b \rangle \Psi^{bb}$$

$$(1 + \partial_a)(1 + \partial_b)\Psi^{ab} = Q^{ab}$$

$$\rightarrow \mathcal{S}_2[\Psi, \hat{Q}] = \frac{1}{2} (i\hat{Q}, \Psi) \begin{bmatrix} a & b \\ c & 0 \end{bmatrix} \begin{pmatrix} i\hat{Q} \\ \Psi \end{pmatrix}$$



$$\mathcal{A} \langle \Psi^{ab} i\hat{Q}^{cd} \rangle = \frac{1}{2N} [\delta_{ac}\delta_{bd} + \delta_{ad}\delta_{bc}]$$

Equation for $\frac{1}{N} \sum_{ij} \chi_{ij}(t, t_0)^2$

$$(1 + \partial_a)(1 + \partial_b) \langle \Psi^{ab} i\hat{Q}^{cd} \rangle = \langle Q^{ab} i\hat{Q}^{cd} \rangle$$

Maximal Lyapunov Exponent $N \gg 1$

* Take $a = c \neq b = d$

$$\left[\partial_a + \partial_b + \partial_a \partial_b - \partial_\Delta^2 V(\Delta; \Delta_0) \right] \langle \Psi^{ab}(t_a, t_b) i\hat{Q}^{ab}(t_c, t_d) \rangle = \frac{1}{2N} \delta(t_a - t_c) \delta(t_b - t_d)$$

Define:

$$t = t_a + t_b, \quad t' = t_c + t_d \\ s = t_a - t_b, \quad s' = t_c - t_d$$

→ $\left[2\partial_t + \partial_t^2 + \mathcal{H}_s \right] \langle \Psi^{ab}(t, s) i\hat{Q}^{ab}(t', s') \rangle = \frac{1}{N} \delta(t - t') \delta(s - s')$

$$\mathcal{H}_s = -\partial_s^2 - \partial_\Delta^2 V(\Delta; \Delta_0) \Big|_{\Delta=\Delta(s)}$$

Fluctuations Quantum Hamiltonian

Write:

$$\langle \Psi^{ab}(t, s) i\hat{Q}^{ab}(t', s') \rangle = \frac{1}{N} \sum_n g_n(t, t') \varphi_n(s) \varphi_n^*(s')$$



Hamiltonian eigenfunctions: $\mathcal{H} \varphi_n = \epsilon_n \varphi_n$

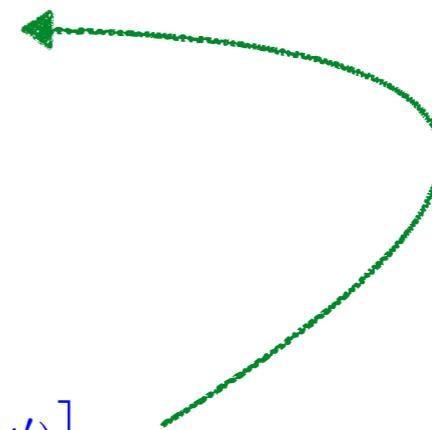
Maximal Lyapunov Exponent $N \gg 1$

→ $[2\partial_t + \partial_t^2 + \epsilon_n] g_n(t, t') = \delta(t - t')$

Fast:

Assume $g_n(t, t') \sim e^{2\lambda_n(t-t')}, \quad t - t' \gg 1$

$$2\lambda_n = -1 \pm \sqrt{1 - \epsilon_n}$$



Slow:

Exact $g_n(t - t') = \frac{\theta(t - t')}{\sqrt{1 - \epsilon_n}} e^{-(t-t')} \sinh[\sqrt{1 - \epsilon_n}(t - t')]$

Finally:

$$\lambda = \max_n \lambda_n = \lambda_0 = \frac{1}{2} [-1 + \sqrt{1 - \epsilon_0}]$$

Maximal Lyapunov exponent

$$\epsilon_0 := \text{lowest eigenvalue of } \mathcal{H} \quad \rightarrow \quad \epsilon_0 < 0 \quad \Rightarrow \quad \lambda > 0$$

Maximal Lyapunov Exponent $N \gg 1$

$$\Rightarrow V_{QM} = -\partial_{\Delta}^2 V(\Delta; \Delta_0) = 1 - g^2 \int Dz \left[\int Dx \phi' \left(gx\sqrt{\Delta_0 - |\Delta|} + gz\sqrt{|\Delta|} \right) \right]^2$$

**)* $\underline{g < 1 \Rightarrow \Delta = \Delta_0 = 0}$

$$[\phi'(0) = 1] \quad V_{QM} = 1 - g^2 \quad \Rightarrow \quad \epsilon_0 = 1 - g^2$$

$$\lambda = \frac{1}{2}(-1 + g) < 0, \quad g < 1$$

**)* $\underline{g > 1 \text{ decaying solution } \Delta(t) \sim e^{-t/\tau_a}, \quad t \gg 1}$

$$\Rightarrow \epsilon_0 < 0$$

$$\boxed{\lambda > 0 \quad g > 1}$$

Chaotic Solution

Limits

$$\lambda \sim \frac{1}{4}(g - 1)^2 \quad g \rightarrow 1^+$$

$$\lambda \sim C \ln g \quad g \rightarrow \infty$$

$$\lambda^{-1} \gg \tau_a \sim (g - 1)^{-1}$$

$$\lambda^{-1} \ll \tau_a \sim 1/\sqrt{1 - 2/\pi}$$

(PRM Theory)

$$2C = 1/\sqrt{(\pi - 2)(2 - \pi/2)} \simeq 1.4286\dots$$

Final Remarks

That's enough...

→ Dynamic Field Theory Formulation

→ Mean Field Limit

Exact in this model (fully connected)

Finite K, D Corrections → Perturbative expansions

Solvable in this model (fully asymmetric)

symmetry → Memory effects

→ Dynamic Mean Field Theory

Starting point perturbative corrections

→ Lyapunov exponent

Thanks for your attention

(and patience)

